



Various state of the art electrical and/or electronic and/or mechanical means of facilitating remote control by the driver D can be employed to achieve this embodiment, particularly with the LED array or lighted liquid crystal panel 4a. The normal position of the driver's eyes ER and EL (Figs. 5,6 and 7), relative to the vehicle A, is critical to the accuracy of the information about the relationship between the clearance path CP defined by the left and right line images 2a and 2b, and the actual left and right road markings or objects in the road. Therefore, this improvement constitutes an important addition to the invention since it permits the driver to position the lines as taught by the informational part of the invention while seated in a normal driving position and posture.

An additional improvement to the previous embodiment is a method of assigning definitive values to the parameters by which the subject driver-visible lines 2a and 2b or lines of marks are remotely located. By this means the correct positioning of said lines could be reestablished using the definitive values for a particular driver. This in turn will allow a number of different drivers of the same vehicle A equipped with the subject invention to reset the definitive values to suit their particular normal driving position and posture. The setting of the correct values for a particular driver could be done either manually or automatically. The automatic embodiment of this improvement of the invention could easily be adapted to the current state of the art automatic systems currently available in some vehicles. These systems set up a number of conditions desired by a particular driver as a result of the entry of a single code number driver identification into the vehicle control system (e.g. existing seat and mirror adjustments).

Fig. 9, shows the driver's view through the windshield 1 of a large vehicle on a road curving to the right, shows another embodiment of this invention which will provide the driver with curved driver-visible left and right lines 32a and 32b, a curved series of lines or curved lines of marks for each side of the vehicle showing the driver the clearance path CP2 it will take if the current setting of the steering wheel 3 is held constant. Using the instantaneous steering wheel